

# Buffer I/O ROT1PROG

S	H1	H2	H3	H4	PH	V1	V2	V3	V4	PV	K	END
57	30..39	30..39	30..39	30	00	00	00	00	00	00	(0F,1F,2F)	20

HEX

K	
0F	Stop
1F	Status
2F	Set

Angle 0 = 360

Driver -> PC (angle)	
H1	* 100
H2	* 10
H3	* 1
H4	0

PC -> Driver (imp)	
H1	* 100
H2	* 10
H3	* 1
H4	0

Example:

Set:

Hor = 123, divider PH=1

angle = 123 + 360 = 483

57	34	38	33	30	01	xx	xx	xx	xx	xx	2F	20
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Stop:

57	xx	xx	xx	xx	xx	xx	xx	xx	xx	xx	0F	20
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xx - any value

Status:

57	xx	xx	xx	xx	xx	xx	xx	xx	xx	xx	xx	1F	20
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xx - any value

When send STOP (0F) or STATUS (2F), from driver receive:

Hor = 123, divider PH=1      **Angle 0 = 360**  
angle = 123 + 360 = 483

57	04	08	03	20
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Notes PH = 1 always